

# Week 5: Bayesian Inference

Bayesian Statistics for Machine Learning

Dr Daniel Worrall

AMLab, University of Amsterdam

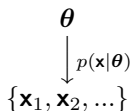
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We are mostly concerned with models which look like

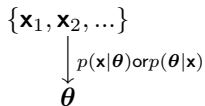
$$p(\mathbf{x}|\boldsymbol{\theta}).$$

In many case  $\mathbf{x}$  refers to an *observation* and  $\boldsymbol{\theta}$  refers to a set of *parameters*.

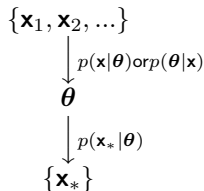
## Probability



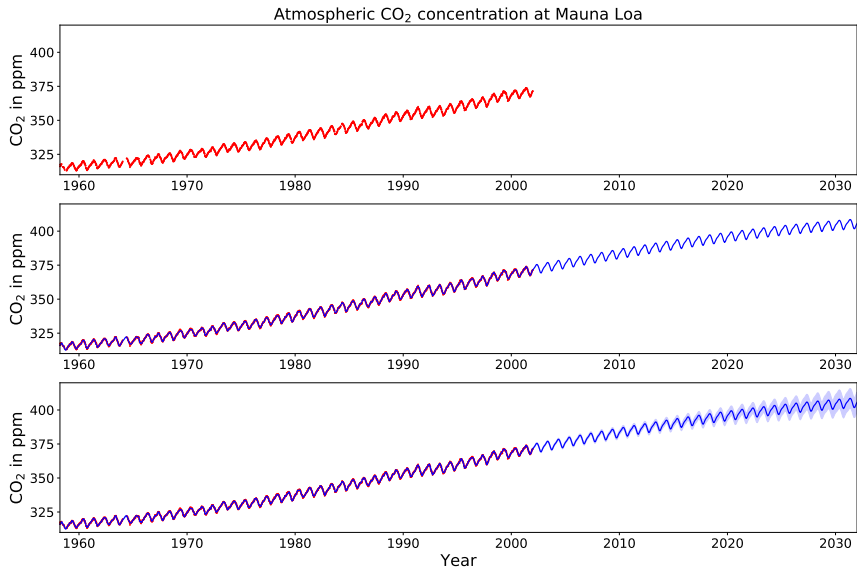
## Statistics



## Machine Learning



In machine learning, we use past data to make predictions about the future.





## I: Bayesian Inference

We previously learnt about maximum likelihood, where we solved

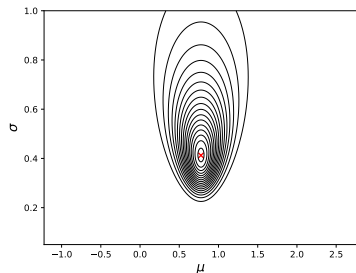
$$\theta_{\text{ML}} = \arg \max_{\theta \in \Theta} p(\mathcal{D}|\theta).$$

- Is this the best we can do?
- It is almost certainly wrong  
 $P(\theta_{\text{ML}} = \theta_{\text{true}}) = 0.$
- In reality  $\mathcal{D} \approx p(\mathcal{D}|\theta)$  but  $\mathcal{D} \sim p_{\text{true}}(\mathcal{D}).$

Why do we want  $\theta_{\text{ML}}$  anyway?

Options

- 1 We are actually interested in knowing  $\theta$
- 2 We don't care: actually want to generate samples  $\{\mathbf{x}_*^{(1)}, \mathbf{x}_*^{(2)}, \dots\}$  from the data generating distribution  $p_{\text{true}}(\mathbf{x}).$





All we need is the *posterior distribution*

$$p(\boldsymbol{\theta}|\mathcal{D})$$

Read, *“the probability of the parameters, given the data”*.

This is way more descriptive than a single point estimate  $\boldsymbol{\theta}_{\text{ML}}$ . It is a probability distribution over the entire space of  $\boldsymbol{\theta}$ , telling us how much each one explains the data.



We compute the posterior using Bayes' theorem

$$p(\boldsymbol{\theta}|\mathcal{D}) = \frac{p(\mathcal{D}|\boldsymbol{\theta})p(\boldsymbol{\theta})}{p(\mathcal{D})}.$$

These terms each have names:

$$\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{evidence}}.$$

Later on we shall dissect this equation in agonising detail, but for now, let's just use it and get a feel for how it works.

NOTE: the evidence also goes by the name of *marginal likelihood*.

e.g. Two TAs are marking exams. If  $x$  denotes the marks awarded by a TA, the distributions of the two markers is

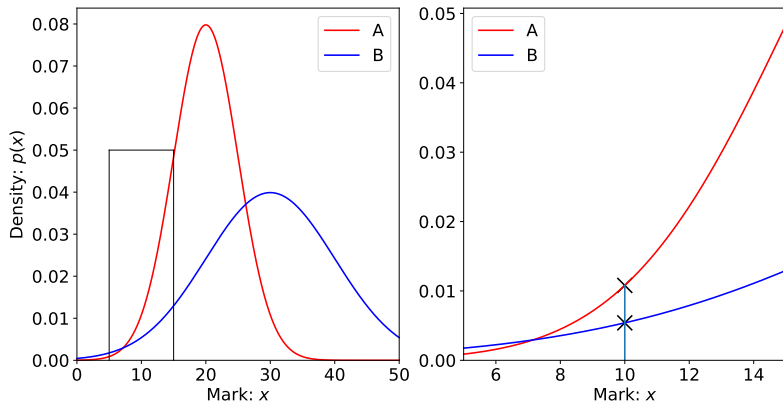
$$p(x|\text{TA}_A) = \mathcal{N}(x; 30, 10^2)$$

$$p(x|\text{TA}_B) = \mathcal{N}(x; 20, 5^2).$$

You flunk your course receiving  $x = 10$  marks. Unethically, you wish to seek out who marked your exam paper. Find the posterior probability that  $\text{TA}_A$  marked your manuscript, assuming you initially expect  $\text{TA}_A$  marked your paper with probability  $\pi = 0.5$ .

$$p(\text{TA}_A|\mathcal{D} = \{10\}) = \frac{p(\mathcal{D}|\text{TA}_A)p(\text{TA}_A)}{p(\mathcal{D})} = \frac{p(\mathcal{D}|\text{TA}_A)p(\text{TA}_A)}{\sum_{i \in \{A,B\}} p(\mathcal{D}|\text{TA}_i)p(\text{TA}_i)}$$





$$\begin{aligned}
 p(\text{TA}_A | \mathcal{D} = \{10\}, \pi) &= \frac{p(\mathcal{D} | \text{TA}_A)p(\text{TA}_A)}{p(\mathcal{D} | \text{TA}_A)p(\text{TA}_A) + p(\mathcal{D} | \text{TA}_B)p(\text{TA}_B)} \\
 &= \frac{\mathcal{N}(10; 30, 10^2)\pi}{\mathcal{N}(10; 30, 10^2)\pi + \mathcal{N}(10; 20, 5^2)(1 - \pi)} \\
 &= \frac{\pi}{\pi + \frac{\mathcal{N}(10; 20, 5^2)}{\mathcal{N}(10; 30, 10^2)}(1 - \pi)}
 \end{aligned}$$

$$\frac{\mathcal{N}(10; 20, 5^2)}{\mathcal{N}(10; 30, 10^2)} = \frac{\frac{1}{5\sqrt{2\pi}} \exp\left\{-\frac{(10-20)^2}{2 \cdot 5^2}\right\}}{\frac{1}{10\sqrt{2\pi}} \exp\left\{-\frac{(10-30)^2}{2 \cdot 10^2}\right\}} = \frac{10e^{-2}}{5e^{-2}} = 2$$

$$p(\text{TA}_A | \mathcal{D} = \{10\}, \pi) = \frac{\pi}{\pi + 2(1 - \pi)}$$

If  $\pi = 0.5$  then  $p(\text{TA}_A | \mathcal{D} = \{10\}, \pi = 0.5) = \frac{1}{3}$ .



Say you get a tip off that  $TA_A$  marked 80% of the manuscripts. What now is your posterior belief that  $TA_A$  marked your paper?

Easy peasy lemon squeezy. We just set the prior to

$$p(TA_A) = \pi = 0.8$$

So

$$p(TA_A | \mathcal{D} = \{10\}, \pi = 0.8) = \frac{0.8}{0.8 + 2(1 - 0.8)} = \frac{2}{3}.$$

The Bayesian framework allows us to incorporate *prior knowledge* into our inferences. How would we achieve this in the maximum likelihood setting?



e.g. This is the original inference problem studied by Thomas Bayes in 1763.

You are given a bent coin. You flip it  $N$  times. It lands heads  $H$  times. If we denote the probability of the coin landing heads as  $\pi$ , what is the ML solution and the posterior distribution  $p(\pi|\mathcal{D})$ ?

**ML solution** If heads is 1, we have  $p(x|\pi) = \pi^x(1 - \pi)^{1-x}$ , so

$$\begin{aligned}\mathcal{L}(\pi) &= \sum_{i=1}^N x_i \log \pi + (1 - x_i) \log(1 - \pi) \\ &= H \log \pi + (N - H) \log(1 - \pi)\end{aligned}$$

which has a maximum at

$$\pi_{\text{ML}} = \frac{H}{N}.$$

**Bayesian solution** Always start with Bayes' Theorem

$$p(\pi|\mathcal{D}) = \frac{p(\mathcal{D}|\pi)p(\pi)}{p(\mathcal{D})} = \frac{\left[\prod_{i=1}^N p(x_i|\pi)\right] p(\pi)}{p(\mathcal{D})}$$

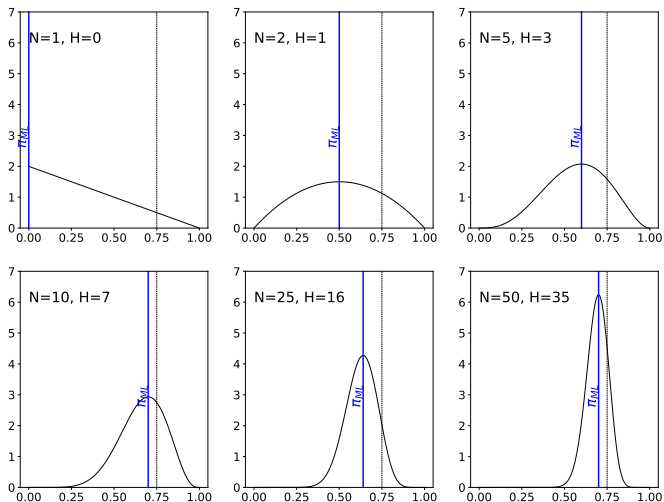
We need a prior, let's pick  $p(\pi) = \text{Uniform}(\pi; 0, 1) = \mathbb{I}[\pi \in [0, 1]]$  for now.

$$\begin{aligned} p(\pi|\mathcal{D}) &= \frac{\left[\prod_{i=1}^N \pi^{x_i} (1 - \pi)^{1-x_i}\right] \mathbb{I}[\pi \in [0, 1]]}{p(\mathcal{D})} \\ &= \frac{[\pi^H (1 - \pi)^{N-H}] \mathbb{I}[\pi \in [0, 1]]}{p(\mathcal{D})} \\ &= \frac{1}{Z} \pi^H (1 - \pi)^{N-H} \end{aligned}$$

# The Bent Coin cont'd



D = [01011101111100110011111001111111111101  
1111100010011]



Notice how the posterior is 'less temperamental' than the likelihood function.

Next we need to figure out the *marginal likelihood*

$$Z = p(\mathcal{D}) = \int p(\mathcal{D}, \pi) d\pi = \int \underbrace{p(\mathcal{D}|\pi)}_{\text{likelihood}} \underbrace{p(\pi)}_{\text{prior}} d\pi.$$

The marginal likelihood is an instance of the famous Beta integral<sup>1</sup>

$$p(\mathcal{D}) = \int_0^1 \pi^H (1 - \pi)^{N-H} d\pi = B(H + 1, N - H + 1) = \frac{H!(N - H)!}{(N + 1)!}$$

$$p(\pi|\mathcal{D}) = \frac{(N + 1)!}{H!(N - H)!} \pi^H (1 - \pi)^{N-H}$$

Don't worry if this integral scares you. It frightens me too! Resources such as Wolfram Alpha, Wikipedia, the Bishop book, and the MacKay book are handy.

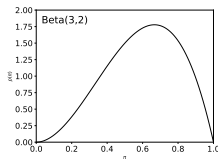
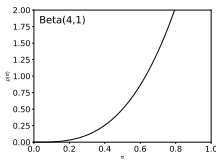
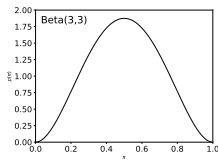
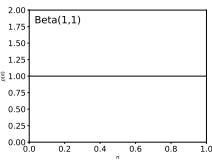
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<sup>1</sup> $B(x, y) = \int_0^1 t^{x-1} (1 - t)^{y-1} dt$

The posterior has the form of a *Beta distribution*

$$\text{Beta}(\pi|\alpha, \beta) = \frac{1}{Z(\alpha, \beta)} \pi^{\alpha-1} (1 - \pi)^{\beta-1}, \quad Z(\alpha, \beta) = \frac{\Gamma(\alpha)\Gamma(\beta)}{\Gamma(\alpha + \beta)}$$

- The Beta distribution is a probability distribution over probabilities.
- The two parameters  $\alpha$  and  $\beta$  control the shape of the distribution.
- The *Gamma* function<sup>2</sup> satisfies  $\Gamma(\alpha) = (\alpha - 1)!$  and  $\Gamma(\alpha + 1) = \alpha\Gamma(\alpha)$ .
- The mean of the distribution is  $\mathbb{E}[\pi] = \frac{\alpha}{\alpha + \beta}$ .




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<sup>2</sup> $\Gamma(\alpha) := \int_0^\infty x^{\alpha-1} e^{-x} dx$





So, we see that the posterior distribution gets sharper and sharper as  $N$  increases. In fact it becomes a Dirac delta peak in the limit of infinite data.

Its maximum is called the *maximum a posteriori* or *MAP*. In this example

$$\pi_{\text{MAP}} = \frac{H}{N}$$

which coincides with  $\pi_{\text{ML}}$ . This is not true in general.



We can use the posterior to make predictions. We can compute the probability of the next coin toss as  $p(x_* = \text{head}|\mathcal{D})$ . We can find this by expanding a marginal

$$\begin{aligned}
 p(x_* = \text{head}|\mathcal{D}) &= \int p(x_* = \text{head}, \pi|\mathcal{D}) \, d\pi = \int \underbrace{p(x_* = \text{head}|\pi, \mathcal{D})}_{\text{forward likelihood}} \underbrace{p(\pi|\mathcal{D})}_{\text{posterior}} \, d\pi \\
 &= \int_0^1 \pi \cdot \frac{\pi^H (1 - \pi)^{N-H}}{p(\mathcal{D})} \, d\pi = \mathbb{E}_\pi [\text{Beta}(\pi|H + 1, N - H + 1)].
 \end{aligned}$$

This is the mean of the Beta distribution, which is  $\mathbb{E}_\pi \text{Beta}(\pi|a, b) = \frac{a}{a+b}$  so

$$p(x_* = \text{head}|\mathcal{D}) = \frac{H + 1}{N + 2}$$

which is called *Laplace's rule of succession*.



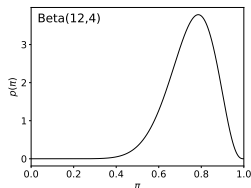
What just happened? We computed a quantity called the *posterior predictive distribution*. It is

$$\underbrace{p(x_*|\mathcal{D})}_{\text{posterior predictive}} = \int_{\Theta} \underbrace{p(x_*|\theta)}_{\text{forward likelihood}} \underbrace{p(\theta|\mathcal{D})}_{\text{posterior}} d\theta$$

If we interpret  $p(x_*|\theta)$  as a particular model of  $x_*$  given the parameters  $\theta$ , then  $p(x_*|\mathcal{D})$  is a weighted average of *all possible models*, where the weights are determined by the posterior i.e. the training data.

Say someone had given us a sneaky hint beforehand that the coin's bias is about 0.7-0.8. We would choose a Beta prior with this mean, say

$$p(\pi) = \text{Beta}(\pi | \alpha = 12, \beta = 4)$$



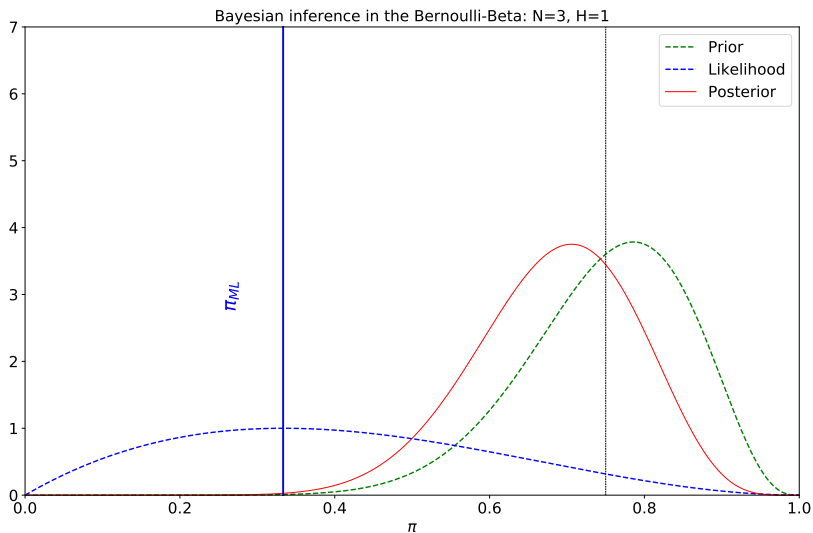
The posterior is

$$p(\pi | \mathcal{D}) = \frac{\overbrace{[\pi^H (1 - \pi)^{N-H}]}^{\text{likelihood}} \cdot \overbrace{\pi^{\alpha-1} (1 - \pi)^{\beta-1}}^{\text{prior}}}{p(\mathcal{D})} = \frac{\pi^{H+\alpha-1} (1 - \pi)^{N-H+\beta-1}}{Z(H + \alpha, N - H + \beta)}$$

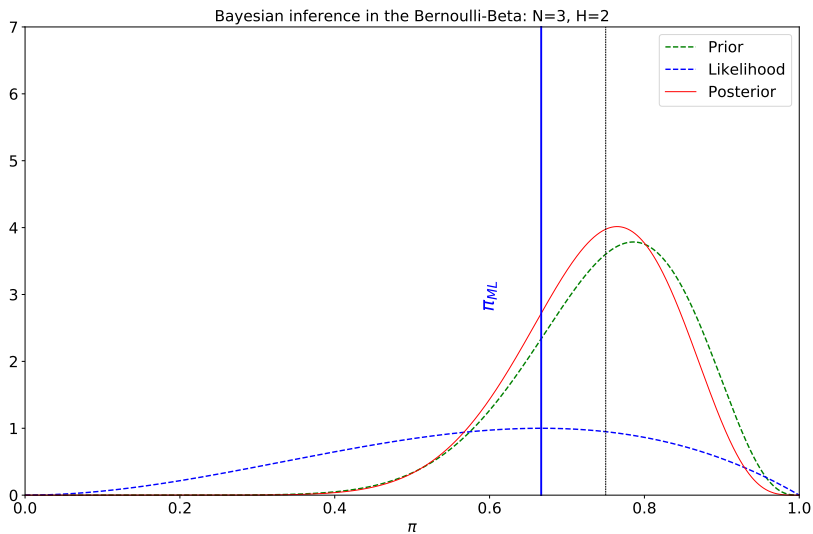
But this is just the Beta distribution, with different parameters!

$$p(\pi | \mathcal{D}) = \text{Beta}(\pi; H + \alpha, N - H + \beta).$$

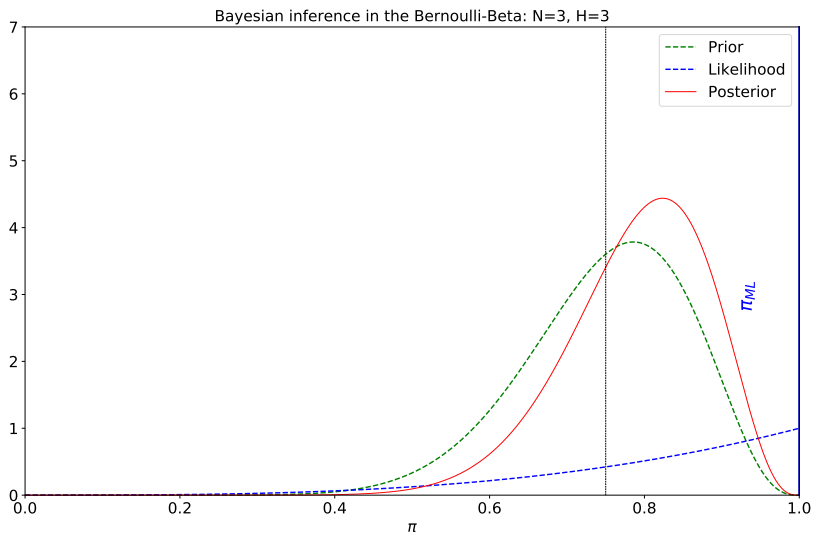
## Bayesian solution

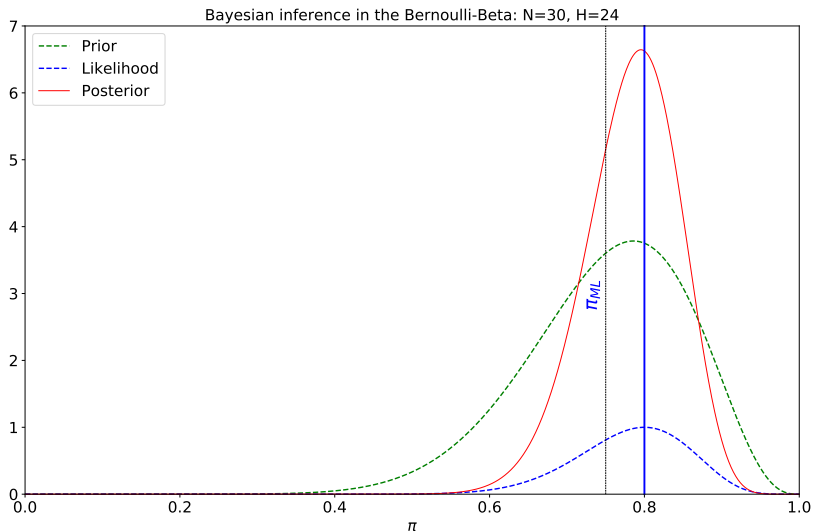


## Bayesian solution

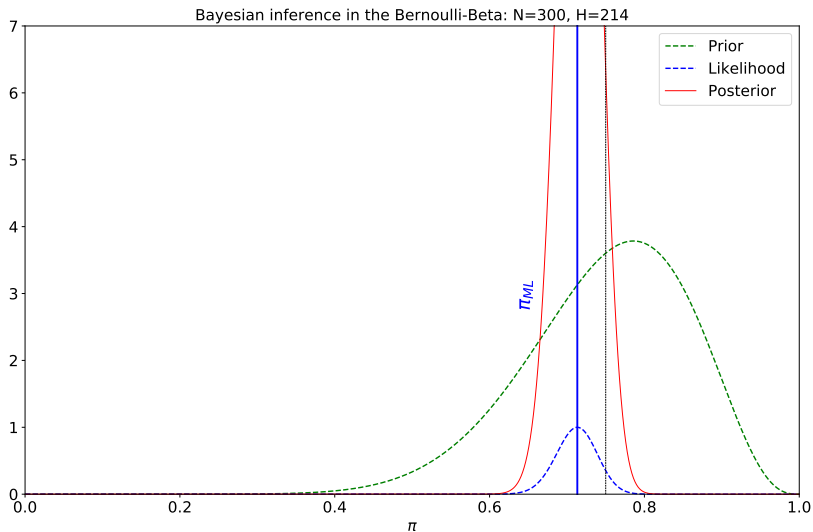


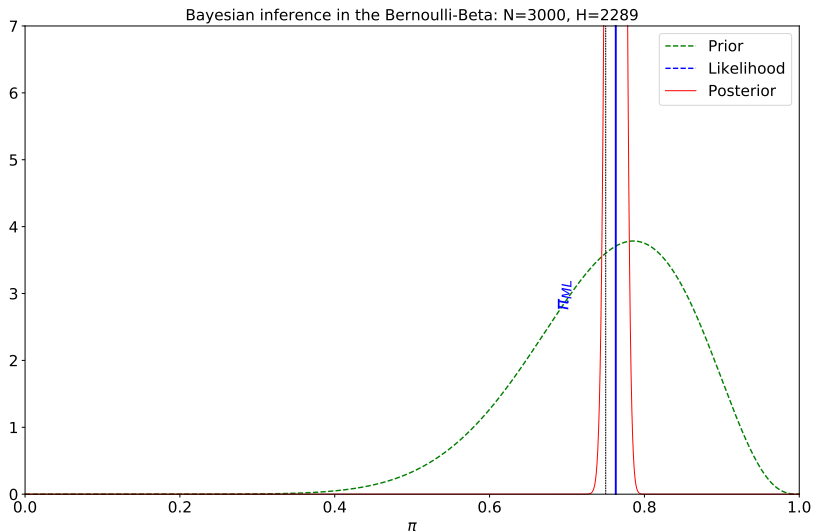
## Bayesian solution

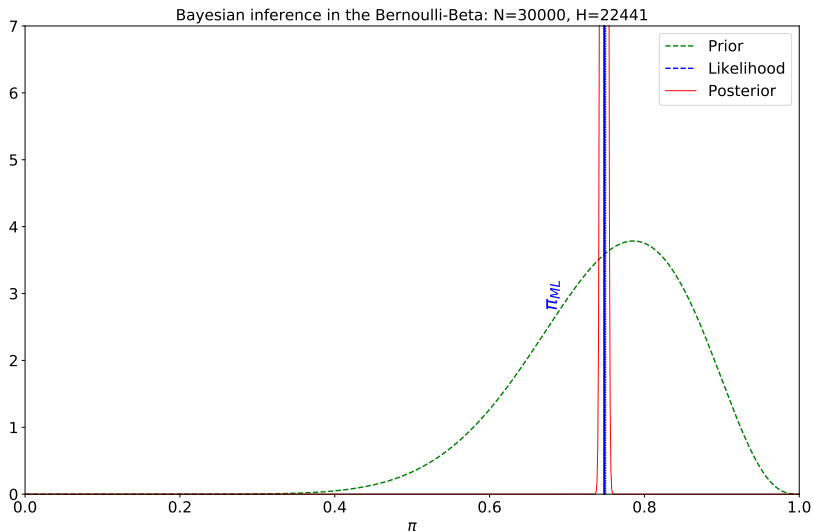


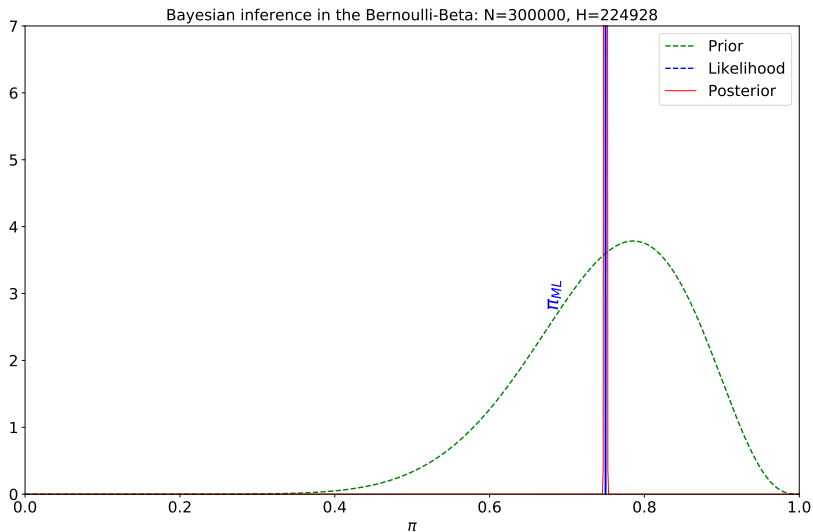








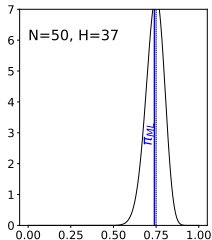
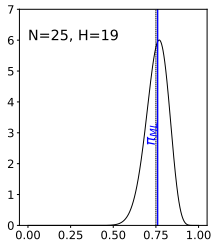
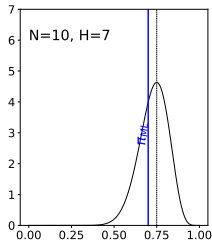
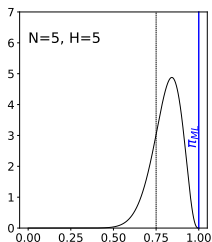
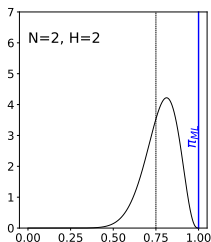
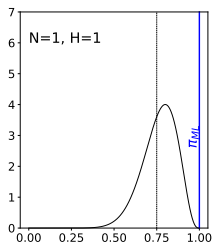




# The Bent Coin cont'd



D = [11111010101011111010111111101111001011011  
11111111111000]





$$p(\pi|\mathcal{D}) = \frac{\pi^{H+\alpha-1}(1-\pi)^{N-H+\beta-1}}{Z(H+\alpha, N-H+\beta)}$$

A couple of things to notice:

- The posterior was a Beta distribution, just like the prior. This property is called *conjugacy*. (More on this later)
- The *MAP* (peak of the posterior) is at

$$\pi_{\text{MAP}} = \frac{H + \alpha - 1}{N + \alpha + \beta - 2} = \frac{\frac{H}{N} + \frac{\alpha-1}{N}}{1 + \frac{\alpha+\beta-2}{N}} = \frac{\pi_{\text{ML}} + \frac{\alpha-1}{N}}{1 + \frac{\alpha+\beta-2}{N}}$$

If you now take the limit  $N \rightarrow \infty$ ,  $\lim_{N \rightarrow \infty} \pi_{\text{MAP}} = \pi_{\text{ML}}$ . So ML and MAP match in the limit. Some would argue that maximum likelihood is a limit case of Bayesian inference.

- The parameters  $\alpha$  and  $\beta$  acts like extra data! They are called *pseudocounts*, with *effective sample size*  $\alpha + \beta$ .

In general, the probability of the next toss is

$$p(x_* = \text{head} | \mathcal{D}, \alpha, \beta) = \frac{H + \alpha + 1}{N + \alpha + \beta + 2} = \frac{\pi_{\text{ML}} + \frac{\alpha+1}{N}}{1 + \frac{\alpha+\beta+2}{N}}$$

Compare this with the prediction from the maximum likelihood  $\pi_{\text{ML}}$ :

$$p(x_* = \text{head} | \pi_{\text{ML}}) = \frac{H}{N}$$

Or maximum *a posteriori*  $\pi_{\text{MAP}}$ :

$$p(x_* = \text{head} | \pi_{\text{MAP}}) = \frac{\pi_{\text{ML}} + \frac{\alpha-1}{N}}{1 + \frac{\alpha+\beta-2}{N}}$$

We have 3 different solutions, which should we prefer?



For a Bernoulli likelihood we can have a Beta prior and posterior. This property is known as *conjugacy*.

Not all likelihoods admit conjugate priors: only distributions in the *exponential family*. Here is a list of likelihoods and their conjugate priors

Distribution	Parameter	Prior
Gaussian	Mean	Gaussian
Gaussian	Variance	Inverse-Gamma
Bernoulli	Mean	Beta
Poisson	Rate ( $\lambda$ )	Gamma
Exponential	Rate ( $\lambda$ )	Gamma
Uniform	Upper limit	Pareto

We like distributions which admit a conjugate prior, because we can find the posterior parameters very efficiently given simple statistics about the input data. Furthermore the posterior distributions are tractable.



Consider a Gaussian likelihood over  $N$  datapoints. To make life easier, we shall reparameterize using the precision  $\lambda = 1/\sigma^2$ , this can be written

$$\begin{aligned}\prod_{i=1}^N \mathcal{N}(x_i | \mu, \lambda^{-1}) &= \prod_{i=1}^N \frac{\lambda}{\sqrt{2\pi}} \exp \left\{ -\frac{\lambda(x_i - \mu)^2}{2} \right\} \\ &= \left( \sqrt{\frac{\lambda}{2\pi}} \right)^N \exp \left\{ -\frac{\lambda}{2} \sum_{i=1}^N (x_i - \mu)^2 \right\}\end{aligned}$$

Let's compute the posterior distribution over the precision, given a conjugate Gamma prior and *fixed mean*

$$p(\lambda | \alpha, \beta) = \frac{1}{Z(\alpha, \beta)} \lambda^{\alpha-1} \exp \{-\beta\lambda\}$$

$$\begin{aligned} p(\lambda|\alpha, \beta, \mu, \{x_i\}) &\propto \left[ \prod_{i=1}^N \mathcal{N}(x_i|\mu, \lambda^{-1}) \right] p(\lambda|\alpha, \beta) \\ &= \left( \frac{\lambda}{2\pi} \right)^{\frac{N}{2}} \exp \left\{ -\frac{\lambda}{2} \sum_{i=1}^N (x_i - \mu)^2 \right\} \frac{1}{Z(\alpha, \beta)} \lambda^{\alpha-1} \exp \{-\beta\lambda\} \\ &\propto \lambda^{\frac{N}{2} + \alpha - 1} \exp \left\{ -\lambda \left( \beta + \frac{1}{2} \sum_{i=1}^N (x_i - \mu)^2 \right) \right\} \end{aligned}$$

This is a new Gamma distribution  $p(\lambda|\alpha', \beta')$  with

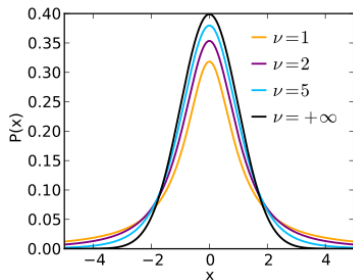
$$\alpha' = \frac{N}{2} + \alpha \quad \beta' = \beta + \frac{1}{2} \sum_{i=1}^N (x_i - \mu)^2$$

Let's look at the posterior predictive distribution.

$$p(x_* | \alpha, \beta, \mu, \{x_i\}) = \int \mathcal{N}(x_* | \mu, \lambda^{-1}) p(\lambda | \alpha', \beta') d\lambda$$

This is in fact the definition of the Student-t distribution. Note that the posterior predictive is not generally the same form as the prior or the forward likelihood.

Models of this form are called Gaussian scale mixtures. They are useful in modelling because they have significantly heavier tails than the Gaussian distribution, which make them robust to outliers.





The categorical distribution is the  $D$ -way generalization of the Bernoulli distribution. It has the form

$$p(\mathbf{x}|\boldsymbol{\pi}) = \pi_1^{x_1} \pi_2^{x_2} \cdots \pi_D^{x_D} = \prod_{d=1}^D \pi_d^{x_d}, \quad \sum_{d=1}^D \pi_d = 1$$

where  $\mathbf{x}$  is *one-hot* i.e. the  $d^{\text{th}}$  entry is 1, the rest are 0. So  $p(x_d|\boldsymbol{\pi}) = \pi_d$ . This is typically used for modelling the distribution of words in sentences, where each word is associated with a label  $x_d$ .

The conjugate prior to the categorical is the *Dirichlet distribution*

$$p(\boldsymbol{\pi}|\boldsymbol{\alpha}) = \text{Dirichlet}(\boldsymbol{\pi}|\boldsymbol{\alpha}) = \frac{1}{Z(\boldsymbol{\alpha})} \prod_{d=1}^D \pi_d^{\alpha_d - 1}.$$

The *hyperparameter*  $\boldsymbol{\alpha}$  controls the shape of the Dirichlet. Each element of  $\boldsymbol{\alpha}$  must satisfy  $\alpha_d > 0$



If for each category we get counts  $\mathbf{N} = [N_1, N_2, \dots, N_D]^\top$ , where  $N = \sum_{d=1}^D N_d$ , the likelihood is

$$\prod_{i=1}^N p(\mathbf{x}_i | \boldsymbol{\pi}) = \prod_{i=1}^N \left( \prod_{d=1}^D \pi_d^{x_{d,i}} \right) = \prod_{d=1}^D \pi_d^{N_d}$$

The posterior distribution is then

$$p(\boldsymbol{\pi} | \{\mathbf{x}_i\}, \boldsymbol{\alpha}) \propto \left[ \prod_{d=1}^D \pi_d^{N_d} \right] \frac{1}{Z(\boldsymbol{\alpha})} \prod_{d=1}^D \pi_d^{\alpha_d - 1} \propto \prod_{d=1}^D \pi_d^{N_d} \pi_d^{\alpha_d - 1} = \prod_{d=1}^D \pi_d^{N_d + \alpha_d - 1}$$

which has the form of a Dirichlet distribution

$$p(\boldsymbol{\pi} | \{\mathbf{x}_i\}, \boldsymbol{\alpha}) = \text{Dirichlet}(\boldsymbol{\pi} | \mathbf{N} + \boldsymbol{\alpha})$$



The posterior predictive is fiddly to work out. It is useful to know that the mean of the  $d^{\text{th}}$  dimension is  $\alpha_d / \sum_{d=1}^D \alpha_d$

$$\begin{aligned} p(x_{*,d} | \{\mathbf{x}_i\}, \boldsymbol{\alpha}) &= \int_{\Delta} p(x_{*,d} | \boldsymbol{\pi}) p(\boldsymbol{\pi} | \{\mathbf{x}_i\}, \boldsymbol{\alpha}) d\boldsymbol{\pi} \\ &= \int_{\Delta} \pi_{*,d} \text{Dirichlet}(\boldsymbol{\pi} | \mathbf{N} + \boldsymbol{\alpha}) d\boldsymbol{\pi} \\ &= \mathbb{E}_{\pi_d} [\text{Dirichlet}(\boldsymbol{\pi} | \mathbf{N} + \boldsymbol{\alpha})] \\ &= \frac{N_d + \alpha_d}{\sum_{d=1}^D N_d + \alpha_d} \end{aligned}$$

We see the role of the prior is to add *pseudocounts* to shift the posterior predictive estimates away from the maximum likelihood solution.

We wanted to compute two quantities

1 The posterior distribution  $p(\pi|\mathcal{D})$

- Use Bayes' theorem for  $p(\pi|\mathcal{D}) = \frac{p(\mathcal{D}|\pi)p(\pi)}{p(\mathcal{D})}$
- Write out the numerator  $p(\mathcal{D}|\pi)p(\pi)$
- Isolate terms in  $\pi$  and match to the form of the prior
- Optionally normalize by  $p(\mathcal{D})$ , which is the marginal of the numerator  
 $p(\mathcal{D}) = \int p(\mathcal{D}|\pi)p(\pi) d\pi$

2 The probability distribution of a test sample  $\mathbf{x}_*$

- This is  $p(\mathbf{x}_*|\mathcal{D})$
- We expand it as  $p(\mathbf{x}_*|\mathcal{D}) = \int p(\mathbf{x}_*|\pi)p(\pi|\mathcal{D}) d\pi$
- This is called the *posterior predictive distribution*

Which distributions have analytical maximum likelihood solutions?

Most of the distributions we have looked at are fairly similar.

They have three main components:

$$p(x|\boldsymbol{\theta}) = \underbrace{\frac{1}{Z(\boldsymbol{\theta})}}_{\text{normalizer}} \cdot \overbrace{b(x)}^{\text{fnc of } x} \cdot \underbrace{\exp\{\boldsymbol{\theta}^\top \mathbf{t}(x)\}}_{\text{exp of linear fnc of } \boldsymbol{\theta}}$$

$\boldsymbol{\theta}$  is called the *natural parameters*, and  $\mathbf{t}(x)$  is called the *sufficient statistics* of the distribution.





A natural choice of prior for the exponential family is

$$p(\boldsymbol{\theta}|\boldsymbol{\tau}, \nu) = \underbrace{\frac{1}{Z(\boldsymbol{\tau}, \nu)}}_{\text{normalizer}} \cdot \overbrace{\left(\frac{1}{Z(\boldsymbol{\theta})}\right)^\nu}^{\text{not a normalizer}} \cdot \exp\{\boldsymbol{\theta}^\top \boldsymbol{\tau}\}$$

$\boldsymbol{\tau}$  and  $\nu$  are hyperparameters called the *pseudo-observations* and *scale* respectively.

**Conjugate exponential posterior** Let's start by looking at the likelihood

$$\begin{aligned} \prod_{i=1}^N p(x_i|\boldsymbol{\theta}) &= \prod_{i=1}^N \frac{1}{Z(\boldsymbol{\theta})} b(x) \exp\{\boldsymbol{\theta}^\top \mathbf{t}(x)\} \\ &= \left(\frac{1}{Z(\boldsymbol{\theta})}\right)^N \left[ \prod_{i=1}^N b(x_i) \right] \exp\left\{\boldsymbol{\theta}^\top \sum_{i=1}^N \mathbf{t}(x_i)\right\} \end{aligned}$$

So the posterior is

$$\begin{aligned} p(\boldsymbol{\theta}|\{x_i\}, \boldsymbol{\tau}, \nu) &\propto \prod_{i=1}^N p(x_i|\boldsymbol{\theta})p(\boldsymbol{\theta}|\boldsymbol{\tau}, \nu) \\ &= \left(\frac{1}{Z(\boldsymbol{\theta})}\right)^N \left[\prod_{i=1}^N b(x_i)\right] \exp\left\{\boldsymbol{\theta}^\top \sum_{i=1}^N \mathbf{t}(x_i)\right\} \cdot \frac{1}{Z(\boldsymbol{\tau}, \nu)} \left(\frac{1}{Z(\boldsymbol{\theta})}\right)^\nu \exp\{\boldsymbol{\theta}^\top \boldsymbol{\tau}\} \\ &\propto \left(\frac{1}{Z(\boldsymbol{\theta})}\right)^{N+\nu} \exp\left\{\boldsymbol{\theta}^\top \left(\boldsymbol{\tau} + \sum_{i=1}^N \mathbf{t}(x_i)\right)\right\} \end{aligned}$$

This is of the same form as the prior, so we know the normalizer is  $Z(\boldsymbol{\tau} + \sum_{i=1}^N \mathbf{t}(x_i), \nu + N)$ , thus

$$p(\boldsymbol{\theta}|\{x_i\}, \boldsymbol{\tau}, \nu) = \frac{Z(\boldsymbol{\theta})^{-(N+\nu)}}{Z(\boldsymbol{\tau} + \sum_{i=1}^N \mathbf{t}(x_i), \nu + N)} \exp\left\{\boldsymbol{\theta}^\top \left(\boldsymbol{\tau} + \sum_{i=1}^N \mathbf{t}(x_i)\right)\right\}$$